

## SPECIFICATION

### MULTI MACHINE INSPECTION SYSTEM

5           The present invention relates to machines,  
which inspect bottles for defects and more  
particularly to a system, which includes a number of  
such machines collectively evaluating a bottle.

### 10           BACKGROUND OF THE INVENTION

Machines for inspecting glass bottles conduct a  
great variety of inspections including an inspection  
for the mold cavity data so that an operator will  
15 know where a defective bottle was made and can  
promptly adjust the bottle making process to elimin-  
ate the problem at that mold. Conventionally a  
single machine can only handle a limited number of  
inspections and as a result a number of machines  
20 will sequentially receive the bottle to be inspected  
and together all the required inspections will be  
completed.

Each machine has its own inspection system,  
which will determine whether any processed bottle  
25 has passed or failed each of the inspections  
conducted by the machine. Conventionally, a  
machine's data is transmitted to a supervisory  
computer, which receives similar data from the other  
machines and combines the data for subsequent use.

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### OBJECT OF THE INVENTION

It is an object of the present invention to  
provide a system for inspecting glass containers,  
35 which is defined by a number of machines which  
eliminates the requirement of a supervisory  
computer.

Other objects and advantages of the present invention will become apparent from the following portion of this specification and from the accompanying drawings which illustrate, in  
5 accordance with the mandate of the patent statutes, a presently preferred embodiment incorporating the principles of the invention.

#### **BRIEF DESCRIPTION OF THE DRAWINGS**

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Figure 1 is an elevational schematic view of a system for inspecting bottles; and

Figure 2 is a logic diagram for the processor of each of the machines shown in Figure 1.

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#### **BRIEF DESCRIPTION OF THE PREFERRED EMBODIMENT**

Figure 1 shows a number of inspection machines M1, M2, Mn which sequentially inspect a bottle 10.

20 The bottle is conveyed through the machines via any number of conveyors 12 which could include belt conveyors which support the bottom of a bottle or devices which have opposed pairs of belts which grip the side wall of a bottle, for example. An encoder  
25 14 is associated with each conveyor so that the position of a bottle can be tracked through the machine. Also present at the entry of each machine is a part present sensor 16 and a rejector 18 is located following the discharge of a bottle from the  
30 last machine.

Each machine has an inspection system 19, which includes a number of inspection stations 20 (more than one inspection could be performed at a single station). The processor 22 in each inspection  
35 system will identify the bottle being inspected as the part passes the bottle present sensor and will

inspect the bottle. At the completion of the inspection processes carried out by a machine, the processor will know whether or not any of the inspections carried out by that machine indicate  
5 that the bottle should be rejected. As can be seen from figure 1, neighboring processors are connected via an Ethernet cable 24. Referring to Figure 2, the query "Is there an Upstream Machine" 30 will be answered in the negative for the processor in the  
10 most upstream location. Accordingly, this processor will form its data into an Ethernet Packet and Pass Ethernet Packet To Next Downstream Machine 32.

This query will be answered in the affirmative for any downstream processor and a downstream  
15 processor will Combine Ethernet Packet From Next Upstream Machine With Inspection Data 34. Where the machine is a middle machine (one that has a machine on either side) the query "Is There A Downstream Machine?" 36 will be answered in the affirmative and  
20 the processor of that machine will Transmit Ethernet Packet Of Combined Data To Next Downstream Machine 38. The combined data will be the data received via the Ethernet packet from the next upstream machine and the inspection data for the machine. The  
25 processor of the most downstream machine accordingly functions as a supervisory computer having all the data of all the inspection machines.